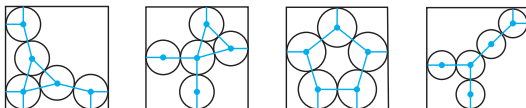


topology of hard disks in a box

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setup

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In statistical mechanics these balls are often called “hard spheres,” or in the two-dimensional setting “hard disks”.

One might expect that the configuration space $\text{Conf}(n, r)$ for small r to be homotopy equivalent to the configuration space $\text{Conf}(n)$ of n distinct points in \mathcal{B} . On the other hand, for r sufficiently large the space $\text{Conf}(n, r)$ is empty; indeed finding the largest r such that $\text{Conf}(n, r) \neq \emptyset$ is the *sphere packing problem*. Sphere packing in bounded regions is a well studied problem — for example in the works of Graham et al and Melissen.

algorithmic roots

There are several situations where the configuration spaces $\text{Conf}(n, r)$ appear:

- Packing problems are an important example. One often looks for a dense (or stable, in some sense) packing by slowly expanding the radii of the disks. To understand how the configuration space changes is a natural question.
- Sampling from the configuration space of hard balls is one of the critical tools in computational statistical physics.
- In robotics, the complexity of algorithms of motion planning for swarms of round robots depends on the topology of the corresponding configuration spaces.

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Studying these kinds of configuration spaces topologically is a natural problem. In a recent survey article Persi Diaconis wrote,

“We know very, very little about the topology of the set of configurations: for fixed n , what are useful bounds on r for the space to be connected? What are the Betti numbers? Of course, for r small this set is connected but very little else is known.”

questions

In fact the topology of $\text{Conf}(n, r)$ may change many times as r varies with n fixed.

One of the main points of this talk is to develop a Morse-theoretic framework for studying these spaces, and as a consequence give an important necessary condition for the topology to change.

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- What is the largest r_* such that $\text{Conf}(n, r)$ is homotopy equivalent to $\text{Conf}(n)$ for $r \in (0, r_*)$, and what happens at r_* ?

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- What is the largest r_* such that $\text{Conf}(n, r)$ is homotopy equivalent to $\text{Conf}(n)$ for $r \in (0, r_*)$, and what happens at r_* ?
- What is the topology of $\text{Conf}(n, r)$ for various asymptotic regimes?

We are mostly interested in the planar situation, $\mathcal{B} \subset \mathbb{R}^2$, but a big chunk of general story is valid for all dimensions.

tautological function

Fix n , and define $\text{Conf}(n)$ to be the set of ordered n -tuples of distinct points in the domain $\mathcal{B} \subset \mathbb{R}^d$:

$$\text{Conf}(n) = \{\vec{x} = (x_1, \dots, x_n) \mid x_i \in \mathcal{B}, x_i \neq x_j\}.$$

As an open subset of \mathbb{R}^{dn} , $\text{Conf}(n)$ is a smooth manifold.

Let $\tau : \text{Conf}(n) \rightarrow \mathbb{R}$ be defined by

$$\tau(\vec{x}) := \min \left(\frac{1}{2} \min_{i \neq j} d(x_i, x_j), \min_i d(x_i, \partial\mathcal{B}) \right), \quad (1)$$

where $\partial\mathcal{B}$ denotes the boundary of \mathcal{B} .

topology of connectivity space

Then by definition the configuration space of n balls of radius r in \mathcal{B} is given by

$$\text{Conf}(n, r) = \tau^{-1}[r, \infty).$$

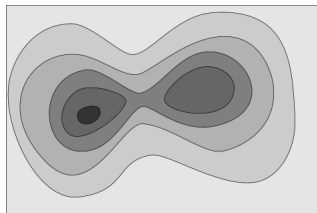
This observation suggests using a 'Morse'-type theory of τ to study the topology of $\text{Conf}(n, r)$ and the topology changes as r varies, and this is our approach.

One obvious trouble on that route is the fact that τ typically is not smooth, so that we need to discuss a general framework which allows us to work with non-smooth functions.

how Morse theory works

The power of Morse theory lies in its ability to localize the changes in topology, as one considers the whole family of sets $\{\tau \geq r\}$.

For the classical Morse theory, where the functions are smooth, and the points are non-degenerate, one can argue that the topology of $\tau^{-1}[r, \infty)$ does not change on an interval $a < r < b$, if there are no critical points of τ with critical values between a and b .



Moreover, one can say what happens near a critical value corresponding to a critical point of index k , as one increases r : a small disk of dimension k is cut off.

configuration spaces

If we implement this approach for our tautological function τ , we need first to understand the “initial condition”, the topology of

$$\{\tau \geq \epsilon\}$$

for some small enough ϵ .

This space is easy to see to be (homotopy equivalent to) the “classical” configuration space of n points in \mathbb{R}^d , denoted $\text{Conf}_o(n)$.

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This is already a very interesting space; luckily a lot is known about it. For example, on the plane, one has

$$\sum \beta_i(\text{Conf}_\circ(n))t^i = (1+t)(1+2t)\cdots(1+(n-1)t).$$

(Here β_i is the rank of the i -th homology group, roughly measuring the number of holes of dimension i .)

min-type functions

The tautological function τ is a *min*-type functions, that is the functions on a manifold M given as the minimum of a parametric family

$$\tau(x) := \min_p f(p, x), x \in M, p \in P,$$

where P is a compact, and f is continuously differentiable in x .

Indeed, we can take P to be the disjoint union of the discrete set corresponding to pairs $(i, j), 1 \leq i < j \leq n$ and of the boundary ∂B .

Such functions are typically not smooth, yet one can create a pretty good version of Morse theory for them.

regular and critical values

For a *min*-type function τ , the set $N \subset P \times M$ defined by

$$N := \{(p, x) : f(p, x) = \tau(x)\}.$$

It is compact, and the slices

$$N_x := \{p \in P : (p, x) \in N\}$$

are *upper semi-continuous*: for any $x \in M$ there exist open neighborhood $U_x \ni x$ and an open neighborhood $UN_x \supset N_x$ such that for $x' \in U_x$, $N_{x'} \subset UN_x$.

For $x \in M$ consider the intersection of the open half-spaces

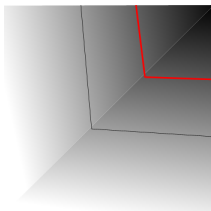
$$H_x(p) := \{v : \langle df_p|_x, v \rangle > 0\}$$

over all $p \in N_x$. This is an open convex cone

$$C_x^\circ := \bigcap_{p \in N_x} H_x(p).$$

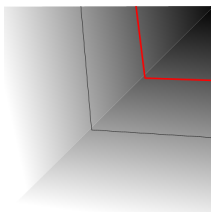
context: configuration spaces

Theorem 1 *If the cones C_x° are non-empty over the level set $\tau^{-1}(c)$, then c is topologically regular.*



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For general *min*-type functions this is essentially the best possible condition for the regularity of the critical values. If the functions f_p are *quasi-convex*, i.e. have convex lower excursion sets $\{f_p \leq c\}$, then 1 can be considerably strengthened.

stress graphs

Corollary 1 implies that unless the level set of the tautological function $\{\tau = r\}$ contains a point x with $C_x^o =$, the homotopy type of $\text{Conf}(n, r)$ is locally constant at r .

By Farkas lemma, the fact that $C_x^o =$ implies that there exists a finite collection of points $p_i \in N_x, i = 1, \dots, l \leq \dim M + 1$, and positive weights $w_i > 0$ such that

$$\sum_i w_i df_{p_i}|_x = 0. \quad (2)$$

In our situation, the convex combination 2 has a clear geometric interpretation.

stress graphs, cont'd

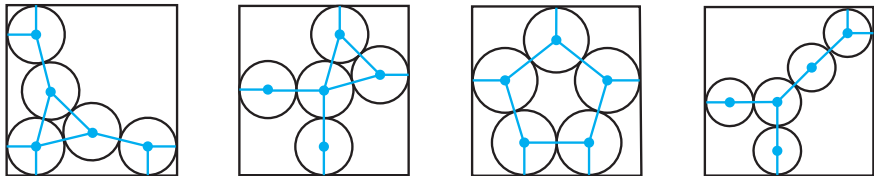
In the construction above, the points p_i correspond either to the pairs of points x_{a_i}, x_{b_i} at distance $2r$, or to the pairs of points $x_{c_i}, y_i, b_i \in \partial\mathcal{B}$, such the distance from x_{c_i} to the boundary is r and is realized at y_i . (Here $r = \tau(x)$, the critical value at the critical point x .)

To such system of weights $w = \{w_i\}$ we associate a *graph* $\Gamma(w)$ embedded into \mathbb{R}^d whose vertices are the points x_1, \dots, x_n , and the boundary points b_l . The edge connects the pairs x_{a_i}, x_{b_i} or x_{c_i}, y_i and has the positive weight w_i .

We interpret this graph as a system of *mechanical stresses*. The points x_i are referred to as the *internal points* of the graph; the points b_i as the *boundary points*.

stress graphs, cont'd

Proposition 1 For any internal vertex x_i , the sum of the stresses acting on it vanishes.



Corollary 1 The sum of unit normals to the boundary components at boundary points belonging to a connected component of $\Gamma(w)$ weighted by w_l vanishes.

first hit

From now on we will restrict to the case of hard spheres in a rectangular box with sides $L := L_1 \leq \dots \leq L_d$.

Lemma 1 *The total length of any connected component of the stress graph is at least L .*

Corollary 2 *The the rectangular box \mathcal{B} , there are no critical values of τ in $(0, L)$, and therefore,*

$$\text{Conf}(n, r) \cong \text{Conf}_o$$

for $0 < r < r_* = L/n$.

what happens at r_* ?

We can in fact very precisely describe what happens at r_* .

Let $i = (n - 1)(d - 1)$. Then for sufficiently small $\epsilon > 0$,

$$\beta_i(\mathbf{Conf}(n, r - \epsilon), \mathbf{Conf}(n, r + \epsilon)) = (n - 1)!,$$

and for all other $k \neq i$, $\beta_k(\mathbf{Conf}(n, r - \epsilon), \mathbf{Conf}(n, r + \epsilon)) = 0$. In other words, one acquires $n!$ new 'holes' in dimension i .

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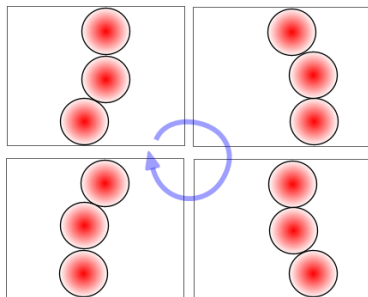
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One can even visualize these new cycles.



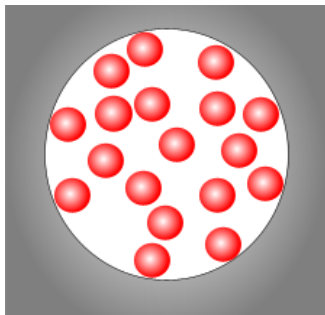
asymptotic regimes

- sparse regime: $rn = O(1)$
- intermediate: $r^k n \rightarrow \infty, r^{k+1} n \rightarrow 0$.
- dense: $r^d n = O(1)$.

Most interesting for physicists regime is dense regime (phase transition to solid).

For us, intermediate regimes are most interesting.

On the plane, the intermediate regime is $rn \rightarrow \infty, r^2 n \rightarrow 0$. Is the configuration space connected? Far from obvious!



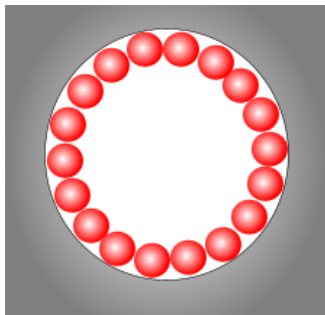
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topological complexity

In the context of this talk, the *topological complexity* a space is the logarithm of its total Betti number *normalized by $n!$* :

For a field \mathbb{F} , define by

$$\beta_k(\text{Conf}(n, r)) = \text{rank } H^k(\text{Conf}(n, r), \mathbb{F}),$$

the rank of k -th homology group of $\text{Conf}(n, r)$.

Definition 1 *The topological complexity of $\text{Conf}(n, r)$ is the*

$$\beta_*(n) = \log \frac{\sum_k \beta_k}{n!}.$$

For example, for $0 < r < r_*$, $\beta_* = 0$.

asymptotics in the sparse regime

For planar configurations in a not too complicated box, the topological complexity behaves pretty reasonably on the intermediate regime:

Theorem 2 For $d = 2$, let $nr \rightarrow \infty$, $nr^2 \rightarrow 0$. If the box \mathcal{B} has semi-algebraic boundary, then

$$\beta_*(n) = \Theta(n).$$

In other words, the total Betti number (up to $n!$ factor) behaves “thermodynamically”.

This should be compared with the “topological conjecture” in statistical physics.

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There are many further questions to explore, about **Conf** and related spaces - stay tuned.

The End